Multiple sign-changing and semi-nodal solutions for coupled Schrödinger equations*

Zhijie Chen¹, Chang-Shou Lin², Wenming Zou³

1,3 Department of Mathematical Sciences, Tsinghua University, Beijing 100084, China

² Taida Institute for Mathematical Sciences, Center for Advanced Study in Theoretical Science, National Taiwan University, No.1, Sec. 4, Roosevelt Road, Taipei 106, Taiwan

Abstract

We study the following coupled Schrödinger equations which have appeared as several models from mathematical physics:

$$\begin{cases} -\Delta u_1 + \lambda_1 u_1 = \mu_1 u_1^3 + \beta u_1 u_2^2, & x \in \Omega, \\ -\Delta u_2 + \lambda_2 u_2 = \mu_2 u_2^3 + \beta u_1^2 u_2, & x \in \Omega, \\ u_1 = u_2 = 0 \text{ on } \partial\Omega. \end{cases}$$

Here $\Omega \subset \mathbb{R}^N (N=2,3)$ is a smooth bounded domain, $\lambda_1, \lambda_2, \mu_1, \mu_2$ are all positive constants. We show that, for each $k \in \mathbb{N}$ there exists $\beta_k > 0$ such that this system has at least k sign-changing solutions (i.e., both two components change sign) and k semi-nodal solutions (i.e., one component changes sign and the other one is positive) for each fixed $\beta \in (0, \beta_k)$.

1 Introduction

In this paper we study solitary wave solutions of the coupled Gross-Pitaevskii equations (cf. [7]):

$$\begin{cases}
-i\frac{\partial}{\partial t}\Phi_{1} = \Delta\Phi_{1} + \mu_{1}|\Phi_{1}|^{2}\Phi_{1} + \beta|\Phi_{2}|^{2}\Phi_{1}, & x \in \Omega, \ t > 0, \\
-i\frac{\partial}{\partial t}\Phi_{2} = \Delta\Phi_{2} + \mu_{2}|\Phi_{2}|^{2}\Phi_{2} + \beta|\Phi_{1}|^{2}\Phi_{2}, & x \in \Omega, \ t > 0, \\
\Phi_{j} = \Phi_{j}(x,t) \in \mathbb{C}, \quad j = 1, 2, \\
\Phi_{j}(x,t) = 0, \quad x \in \partial\Omega, \ t > 0, \ j = 1, 2,
\end{cases}$$
(1.1)

^{*}Chen and Zou are supported by NSFC (11025106). E-mail: chenzhijie1987@sina.com (Chen); cslin@math.ntu.edu.tw (Lin); wzou@math.tsinghua.edu.cn (Zou)

where $\Omega \subset \mathbb{R}^N(N=2,3)$ is a smooth bounded domain, i is the imaginary unit, $\mu_1, \mu_2 > 0$ and $\beta \neq 0$ is a coupling constant. System (1.1) arises in mathematical models from several physical phenomena, especially in nonlinear optics. Physically, the solution Φ_i denotes the j^{th} component of the beam in Kerr-like photorefractive media (cf. [1]). The positive constant μ_j is for selffocusing in the j^{th} component of the beam, and the coupling constant β is the interaction between the two components of the beam. Problem (1.1) also arises in the Hartree-Fock theory for a double condensate, i.e., a binary mixture of Bose-Einstein condensates in two different hyperfine states $|1\rangle$ and $|2\rangle$ (cf. [13]). Physically, Φ_i are the corresponding condensate amplitudes, μ_i and β are the intraspecies and interspecies scattering lengths. Precisely, the sign of μ_i represents the self-interactions of the single state $|j\rangle$. If $\mu_i > 0$ as considered here, it is called the focusing case, in opposition to the defocusing case where $\mu_i < 0$. Besides, the sign of β determines whether the interactions of states $|1\rangle$ and $|2\rangle$ are repulsive or attractive, i.e., the interaction is attractive if $\beta > 0$, and the interaction is repulsive if $\beta < 0$.

To study solitary wave solutions of (1.1), we set $\Phi_j(x,t) = e^{i\lambda_j t}u_j(x)$ for j=1,2. Then system (1.1) is reduced to the following elliptic system

$$\begin{cases}
-\Delta u_1 + \lambda_1 u_1 = \mu_1 u_1^3 + \beta u_1 u_2^2, & x \in \Omega, \\
-\Delta u_2 + \lambda_2 u_2 = \mu_2 u_2^3 + \beta u_1^2 u_2, & x \in \Omega, \\
u_1 = u_2 = 0 \text{ on } \partial\Omega.
\end{cases}$$
(1.2)

Definition 1.1. We call a solution (u_1, u_2) nontrivial if $u_j \not\equiv 0$ for j = 1, 2, a solution (u_1, u_2) semi-trivial if (u_1, u_2) is type of $(u_1, 0)$ or $(0, u_2)$. A solution (u_1, u_2) is called positive if $u_j > 0$ in Ω for j = 1, 2, a solution (u_1, u_2) sign-changing if both u_1 and u_2 change sign, a solution (u_1, u_2) semi-nodal if one component is positive and the other one changes sign.

In the last decades, system (1.2) has received great interest from many mathematicians. In particular, the existence and multiplicity of *positive* solutions of (1.2) have been well studied in $[2, 3, 5, 6, 9, 12, 15, 16, 19, 20, 22, 23, 24, 27, 28] and references therein. Note that all these papers deal with the subcritical case <math>N \leq 3$. Recently, Chen and Zou [8] studied the existence and properties of *positive* least energy solutions of (1.2) in the critical case N = 4.

On the other hand, there are few results about the existence of sign-changing or semi-nodal solutions to (1.2) in the literature. When $\beta > 0$ is sufficiently large, multiple radially symmetric sign-changing solutions of (1.2) were constructed in [21] for the entire space case. Remark that the method in [21] can not be applied in the non-radial bounded domain case. Recently, the authors [10] proved the existence of infinitely many sign-changing solutions of (1.2) for each fixed $\beta < 0$. Independently, Liu, Liu and Wang [17] obtained infinitely many sign-changing solutions of a general m-coupled system ($m \ge 2$) for each fixed $\beta < 0$. The methods in [10, 17] are completely different.

The main goal of this paper is to study the existence of sign-changing and semi-nodal solutions when $\beta > 0$ is small. This will complement the study made in [10, 17, 21]. Our first result is as follows.

Theorem 1.1. Let $\Omega \subset \mathbb{R}^N (N=2,3)$ be a smooth bounded domain and $\lambda_1, \lambda_2, \mu_1, \mu_2 > 0$. Then for any $k \in \mathbb{N}$ there exists $\beta_k > 0$ such that system (1.2) has at least k sign-changing solutions for each fixed $\beta \in (0, \beta_k)$.

Definition 1.2. A nontrivial solution is called a least energy solution, if it has the least energy among all nontrivial solutions. A sign-changing solution is called a least energy sign-changing solution, if it has the least energy among all sign-changing solutions.

Lin and Wei [16] proved that there exists $\beta_0 > 0$ small such that, for any $\beta \in (-\infty, \beta_0)$, (1.2) has a least energy solution which turns out to be positive. Recently, the existence of least energy sign-changing solutions for $\beta < 0$ was proved in [10]. Here we can prove the following result.

Theorem 1.2. Let assumptions in Theorem 1.1 hold. Then there exists $\beta'_1 \in (0, \beta_1]$ such that system (1.2) has a least energy sign-changing solution for each $\beta \in (0, \beta'_1)$.

Theorems 1.1 and 1.2 are both concerned with sign-changing solutions. The following result is about the existence of multiple semi-nodal solutions.

Theorem 1.3. Let assumptions in Theorem 1.1 hold. Then for any $k \in \mathbb{N}$ there exists $\beta_k > 0$ such that, for each $\beta \in (0, \beta_k)$, system (1.2) has at least k semi-nodal solutions with the first component sign-changing and the second component positive.

Remark 1.1. Similarly we can prove that (1.2) has at least k semi-nodal solutions with the first component positive and the second one sign-changing for each $\beta \in (0, \beta_k)$. Recently, [25, Theorem 0.2] proved the existence of $\beta_k > 0$ such that, for each $\beta \in (0, \beta_k)$, (1.2) has at least k nontrivial solutions $(u_{1,i}, u_{2,i})$ with $u_{1,i} > 0$ in Ω ($i = 1, \dots, k$). These solutions are called semi-positive solutions in [25]. Remark that whether $u_{2,i}$ is positive or sign-changing is not known in [25], hence our result improves [25, Theorem 0.2] clearly. Our proofs here are quite different from [25].

Remark 1.2. Theorems 1.1-1.3 are all stated in the bounded domain case. Consider the following elliptic system in the entire space:

$$\begin{cases}
-\Delta u_1 + \lambda_1 u_1 = \mu_1 u_1^3 + \beta u_1 u_2^2, & x \in \mathbb{R}^N, \\
-\Delta u_2 + \lambda_2 u_2 = \mu_2 u_2^3 + \beta u_1^2 u_2, & x \in \mathbb{R}^N, \\
u_1(x), u_2(x) \to 0 \quad as \ |x| \to +\infty.
\end{cases}$$
(1.3)

Then by working in the space $H^1_r(\mathbb{R}^N):=\{u\in H^1(\mathbb{R}^N): u \text{ radially symmetric}\}$ and recalling the compactness of $H^1_r(\mathbb{R}^N)\hookrightarrow L^4(\mathbb{R}^N)$, we can prove the following result via the same method: For any $k\in\mathbb{N}$ there exists $\beta_k>0$ such that, for each fixed $\beta\in(0,\beta_k)$, system (1.3) has at least k radially symmetric sign-changing solutions and k radially symmetric semi-nodal solutions. On the other hand, in 2008 Liu and Wang [18] proved the existence of $\beta_k>0$ such that, for each

 $\beta \in (0, \beta_k)$, (1.3) has at least k nontrivial radially symmetric solutions. In fact, they studied a general m-coupled system ($m \ge 2$). Remark that whether solutions obtained in [18] are positive or sign-changing or semi-nodal is not known. Moreover, Liu and Wang [18, Remark 3.6] suspected that solutions obtained in [18] are not positive solutions, but no proof has yet been given. Our results improve the result of [18] in the two coupled case (m=2).

Remark 1.3. After the completion of this paper, we learned that (1.3) has also been studied in a recent manuscript [14], where the authors obtained multiple radially symmetric sign-changing solutions with a prescribed number of zeros for $\beta > 0$ small. Remark that their method can not be applied in the non-radial bounded domain case.

The rest of this paper proves these theorems. We give some notations here. Throughout this paper, we denote the norm of $L^p(\Omega)$ by $|u|_p = (\int_{\Omega} |u|^p dx)^{\frac{1}{p}}$, the norm of $H^1_0(\Omega)$ by $||u||^2 = \int_{\Omega} (|\nabla u|^2 + u^2) dx$ and positive constants (possibly different in different places) by C, C_0, C_1, \cdots . Denote

$$||u||_{\lambda_i}^2 := \int_{\Omega} (|\nabla u|^2 + \lambda_i u^2) \, dx$$

for convenience. Then $\|\cdot\|_{\lambda_i}$ are equivalent norms to $\|\cdot\|$. Define $H:=H^1_0(\Omega)\times H^1_0(\Omega)$ with norm $\|(u_1,u_2)\|^2_H:=\|u_1\|^2_{\lambda_1}+\|u_2\|^2_{\lambda_2}$. The rest of this paper is organized as follows. In Section 2 we give the proof

The rest of this paper is organized as follows. In Section 2 we give the proof of Theorem 1.1. The main ideas of our proof are inspired by [10, 26], where a new *constrained problem* introduced by [10] and a new notion of *vector genus* introduced by [26] will be used to define appropriate minimax values. In [26], Tavares and Terracini studied the following general *m*-coupled system

$$\begin{cases} -\Delta u_j - \mu_j u_j^3 - \beta u_j \sum_{i \neq j} u_i^2 = \lambda_{j,\beta} u_j, \\ u_j \in H_0^1(\Omega), \quad j = 1, \cdots, m, \end{cases}$$

$$(1.4)$$

where $\beta < 0$, $\mu_j \leq 0$ are all fixed constants. Then [26, Theorem 1.1] says that there exist infinitely many $\lambda = (\lambda_{1,\beta}, \cdots, \lambda_{m,\beta}) \in \mathbb{R}^m$ and $u = (u_1, \cdots, u_m) \in H_0^1(\Omega, \mathbb{R}^m)$ such that (u, λ) are sign-changing solutions of (1.4). That is, $\lambda_{j,\beta}$ is not fixed a *priori* and appears as a Lagrange multiplier in [26]. Here we deal with the focusing case $\mu_j > 0$, and $\lambda_j, \mu_j, \beta > 0$ are all fixed constants. Some arguments in our proof are borrowed from [10, 26] with modifications. Although some procedures are close to those in [10, 26], we prefer to provide all the necessary details to make the paper self-contained. In Section 3 we will use a minimizing argument to prove Theorem 1.2. By giving some modifications to arguments in Sections 2 and 3, we will prove Theorems 1.3 in Section 4.

2 Proof of Theorem 1.1

In the sequel we let assumptions in Theorem 1.1 hold. Without loss of generality we assume that $\mu_1 \geq \mu_2$. Let $\beta \in (0, \mu_2)$. Note that solutions of (1.2) correspond

to the critical points of C^2 functional $E_\beta: H \to \mathbb{R}$ given by

$$E_{\beta}(u_1, u_2) := \frac{1}{2} \left(\|u_1\|_{\lambda_1}^2 + \|u_2\|_{\lambda_2}^2 \right) - \frac{1}{4} \left(\mu_1 |u_1|_4^4 + \mu_2 |u_2|_4^4 \right) - \frac{\beta}{2} \int_{\Omega} u_1^2 u_2^2 dx.$$
(2.1)

Since we are only concerned with nontrivial solutions, we denote $\widetilde{H} := \{(u_1, u_2) \in H : u_i \neq 0 \text{ for } i = 1, 2\}$, which is open in H. Write $\vec{u} = (u_1, u_2)$ for convenience.

Lemma 2.1. For any $\vec{u} = (u_1, u_2) \in \widetilde{H}$, if

$$\begin{cases} \mu_{2}|u_{2}|_{4}^{4}||u_{1}||_{\lambda_{1}}^{2} - \beta||u_{2}||_{\lambda_{2}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx > 0, \\ \mu_{1}|u_{1}|_{4}^{4}||u_{2}||_{\lambda_{2}}^{2} - \beta||u_{1}||_{\lambda_{1}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx > 0, \end{cases}$$

$$(2.2)$$

then system

$$\begin{cases} \|u_1\|_{\lambda_1}^2 = t_1 \mu_1 |u_1|_4^4 + t_2 \beta \int_{\Omega} u_1^2 u_2^2 dx \\ \|u_2\|_{\lambda_2}^2 = t_2 \mu_2 |u_2|_4^4 + t_1 \beta \int_{\Omega} u_1^2 u_2^2 dx \end{cases}$$
(2.3)

has a unique solution

$$\begin{cases}
t_1(\vec{u}) = \frac{\mu_2 |u_2|_4^4 |u_1|_{\lambda_1}^2 - \beta |u_2|_{\lambda_2}^2 \int_{\Omega} u_1^2 u_2^2 dx}{\mu_1 \mu_2 |u_1|_4^4 |u_2|_4^4 - \beta^2 (\int_{\Omega} u_1^2 u_2^2 dx)^2} > 0 \\
t_2(\vec{u}) = \frac{\mu_1 |u_1|_4^4 |u_2|_{\lambda_2}^2 - \beta |u_1|_{\lambda_1}^2 \int_{\Omega} u_1^2 u_2^2 dx}{\mu_1 \mu_2 |u_1|_4^4 |u_2|_{\lambda_2}^2 - \beta |u_1|_{\lambda_1}^2 \int_{\Omega} u_1^2 u_2^2 dx} > 0.
\end{cases} (2.4)$$

Moreover,

$$\sup_{t_1,t_2 \ge 0} E_{\beta} \left(\sqrt{t_1} u_1, \sqrt{t_2} u_2 \right) = E_{\beta} \left(\sqrt{t_1(\vec{u})} u_1, \sqrt{t_2(\vec{u})} u_2 \right)
= \frac{1}{4} \left(t_1(\vec{u}) \|u_1\|_{\lambda_1}^2 + t_2(\vec{u}) \|u_2\|_{\lambda_2}^2 \right)
= \frac{1}{4} \frac{\mu_2 |u_2|_4^4 \|u_1\|_{\lambda_1}^4 - 2\beta \|u_1\|_{\lambda_1}^2 \|u_2\|_{\lambda_2}^2 \int_{\Omega} u_1^2 u_2^2 dx + \mu_1 |u_1|_4^4 \|u_2\|_{\lambda_2}^4 }{\mu_1 \mu_2 |u_1|_4^4 |u_2|_4^4 - \beta^2 \left(\int_{\Omega} u_1^2 u_2^2 dx \right)^2}$$
(2.5)

and $(t_1(\vec{u}), t_2(\vec{u}))$ is the unique maximum point of $E_{\beta}(\sqrt{t_1}u_1, \sqrt{t_2}u_2)$.

Proof. By (2.2) we see that $\mu_1\mu_2|u_1|_4^4|u_2|_4^4-\beta^2(\int_\Omega u_1^2u_2^2dx)^2>0$, so $(t_1(\vec{u}),t_2(\vec{u}))$ defined in (2.4) is the unique solution of (2.3). Note that for $t_1,t_2\geq 0$,

$$f(t_1, t_2) := E_{\beta} \left(\sqrt{t_1} u_1, \sqrt{t_2} u_2 \right) = \frac{1}{2} t_1 \|u_1\|_{\lambda_1}^2 + \frac{1}{2} t_2 \|u_2\|_{\lambda_2}^2$$

$$- \frac{1}{4} \left(t_1^2 \mu_1 |u_1|_4^4 + t_2^2 \mu_2 |u_2|_4^4 \right) - \frac{1}{2} t_1 t_2 \beta \int_{\Omega} u_1^2 u_2^2 dx$$

$$\leq \left(\frac{t_1}{2} \|u_1\|_{\lambda_1}^2 - \frac{t_1^2}{4} \mu_1 |u_1|_4^4 \right) + \left(\frac{t_2}{2} \|u_2\|_{\lambda_2}^2 - \frac{t_2^2}{4} \mu_2 |u_2|_4^4 \right).$$

This implies that $f(t_1, t_2) < 0$ for $\max\{t_1, t_2\} > T$, where T is some positive constant. So there exists $(\tilde{t}_1, \tilde{t}_2) \in [0, T]^2 \setminus \{(0, 0)\}$ such that

$$f(\tilde{t}_1, \tilde{t}_2) = \sup_{t_1, t_2 \ge 0} f(t_1, t_2).$$

It suffices to show that $(\tilde{t}_1, \tilde{t}_2) = (t_1(\vec{u}), t_2(\vec{u}))$. Note that

$$\sup_{t_1 \ge 0} f(t_1, 0) = \frac{1}{4} \frac{\|u_1\|_{\lambda_1}^4}{\mu_1 |u_1|_4^4}.$$

Recalling the expression of $f(t_1(\vec{u}), t_2(\vec{u}))$ in (2.5), by a direct computation we deduce from (2.2) that

$$f(t_1(\vec{u}), t_2(\vec{u})) - \sup_{t_1 \ge 0} f(t_1, 0) = \frac{(\mu_1 |u_1|_4^4 ||u_2||_{\lambda_2}^2 - \beta ||u_1||_{\lambda_1}^2 \int_{\Omega} u_1^2 u_2^2 dx)^2}{4\mu_1 |u_1|_4^4 ||\mu_1||_4^2 ||\mu_1||_4^4 ||u_2||_4^4 - \beta^2 (\int_{\Omega} u_1^2 u_2^2 dx)^2]} > 0.$$

Similarly we have $f(t_1(\vec{u}), t_2(\vec{u})) - \sup_{t_2 \geq 0} f(0, t_2) > 0$, so $\tilde{t}_1 > 0$ and $\tilde{t}_2 > 0$. Then by $\frac{\partial}{\partial t_1} f(t_1, t_2)|_{(\tilde{t}_1, \tilde{t}_2)} = \frac{\partial}{\partial t_2} f(t_1, t_2)|_{(\tilde{t}_1, \tilde{t}_2)} = 0$ we see that $(\tilde{t}_1, \tilde{t}_2)$ satisfies (2.3), so $(\tilde{t}_1, \tilde{t}_2) = (t_1(\vec{u}), t_2(\vec{u}))$.

Define

$$\mathcal{M}^* := \left\{ \vec{u} \in H : 1/2 < |u_1|_4^4 < 2, \ 1/2 < |u_2|_4^4 < 2 \right\};$$

$$\mathcal{M}^*_{\beta} := \left\{ \vec{u} \in \mathcal{M}^* : \vec{u} \text{ satisfies (2.2)} \right\};$$
(2.6)

$$\mathcal{M}_{\beta}^{**} := \left\{ \vec{u} \in \mathcal{M}^{*} : \begin{array}{l} \mu_{2} \|u_{1}\|_{\lambda_{1}}^{2} - \beta \|u_{2}\|_{\lambda_{2}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx > 0 \\ \mu_{1} \|u_{2}\|_{\lambda_{2}}^{2} - \beta \|u_{1}\|_{\lambda_{1}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx > 0 \end{array} \right\};$$

$$\mathcal{M} := \left\{ \vec{u} \in H : |u_{1}|_{4} = 1, |u_{2}|_{4} = 1 \right\}, \quad \mathcal{M}_{\beta} := \mathcal{M} \cap \mathcal{M}_{\beta}^{*}. \tag{2.7}$$

Then $\mathcal{M}_{\beta} = \mathcal{M} \cap \mathcal{M}_{\beta}^{**}$. Evidently \mathcal{M}^{*} , \mathcal{M}_{β}^{*} , \mathcal{M}_{β}^{**} are all open subsets of H and \mathcal{M} is closed. Note that $\mu_{1}\mu_{2} - \beta^{2}(\int_{\Omega}u_{1}^{2}u_{2}^{2}dx)^{2} > 0$ for any $\vec{u} \in \mathcal{M}_{\beta}^{**}$, as in [10] we define a new functional $J_{\beta}: \mathcal{M}_{\beta}^{**} \to (0, +\infty)$ by

$$J_{\beta}(\vec{u}) := \frac{1}{4} \frac{\mu_2 \|u_1\|_{\lambda_1}^4 - 2\beta \|u_1\|_{\lambda_1}^2 \|u_2\|_{\lambda_2}^2 \int_{\Omega} u_1^2 u_2^2 dx + \mu_1 \|u_2\|_{\lambda_2}^4}{\mu_1 \mu_2 - \beta^2 (\int_{\Omega} u_1^2 u_2^2 dx)^2}.$$

A direct computation yields $J_{\beta} \in C^1(\mathcal{M}_{\beta}^{**}, (0, +\infty))$. Moreover, since any $\vec{u} \in \mathcal{M}_{\beta}$ is an interior point of \mathcal{M}_{β}^{**} , by (2.4) we can prove that

$$J_{\beta}'(\vec{u})(\varphi,0) = t_1(\vec{u}) \int_{\Omega} (\nabla u_1 \nabla \varphi + \lambda_1 u_1 \varphi) \, dx - t_1(\vec{u}) t_2(\vec{u}) \beta \int_{\Omega} u_1 u_2^2 \varphi \, dx, \quad (2.8)$$

$$J_{\beta}'(\vec{u})(0,\psi) = t_2(\vec{u}) \int_{\Omega} (\nabla u_2 \nabla \psi + \lambda_2 u_2 \psi) \, dx - t_1(\vec{u}) t_2(\vec{u}) \beta \int_{\Omega} u_1^2 u_2 \psi \, dx \quad (2.9)$$

hold for any $\vec{u} \in \mathcal{M}_{\beta}$ and $\varphi, \psi \in H_0^1(\Omega)$ (Remark that (2.8)-(2.9) do not hold for $\vec{u} \in \mathcal{M}_{\beta}^{**} \setminus \mathcal{M}_{\beta}$). Note that Lemma 2.1 yields

$$J_{\beta}(u_1, u_2) = \sup_{t_1, t_2 > 0} E_{\beta} \left(\sqrt{t_1} u_1, \sqrt{t_2} u_2 \right), \quad \forall (u_1, u_2) \in \mathcal{M}_{\beta}.$$
 (2.10)

To obtain nontrivial solutions of (1.2), we turn to study the functional J_{β} restricted to \mathcal{M}_{β} , which is a problem with two constraints. Define

$$\mathcal{N}_b^* := \left\{ \vec{u} \in \mathcal{M}^* : \|u_1\|_{\lambda_1}^2, \|u_2\|_{\lambda_2}^2 < b \right\}, \quad \mathcal{N}_b := \mathcal{N}_b^* \cap \mathcal{M}. \tag{2.11}$$

Fix any $k \in \mathbb{N}$. Our goal is to prove the existence of $\beta_k > 0$ such that (1.2) has at least k sign-changing solutions for any $\beta \in (0, \beta_k)$. To do this, we let W_{k+1} be a k+1 dimensional subspace of $H_0^1(\Omega)$ which contains an element φ_0 satisfying $\varphi_0 > 0$ in Ω . Then we can find $\bar{b} > 0$ such that

$$||u||_{\lambda_1}^2$$
, $||u||_{\lambda_2}^2 < \bar{b}$, $\forall u \in W_{k+1}$ satisfying $|u|_4^4 < 2$. (2.12)

Fix a b > 0 such that

$$b^2 > (2 + \mu_1/\mu_2)\bar{b}^2.$$
 (2.13)

Then $\mathcal{N}_{\bar{b}}^* \subset \mathcal{N}_b^*$ and $\mathcal{N}_{\bar{b}} \subset \mathcal{N}_b$. Recalling the Sobolev inequality

$$||u||_{\lambda_i}^2 \ge S|u|_4^2, \quad \forall u \in H_0^1(\Omega), \quad i = 1, 2,$$
 (2.14)

where S is a positive constant, we have the following lemma.

Lemma 2.2. There exist $\beta_0 \in (0, \mu_2)$ and $C_1 > C_0 > 0$ such that for any $\beta \in (0, \beta_0)$ there hold $\mathcal{N}_b^* \subset \mathcal{M}_\beta^* \cap \mathcal{M}_\beta^{**}$ and

$$C_0 \le t_1(\vec{u}), t_2(\vec{u}) \le C_1, \quad \forall \vec{u} \in \mathcal{N}_b^*.$$

Proof. Define $\beta_0 := \frac{\mu_2 S}{8b}$ and let $\beta \in (0, \beta_0)$. For any $\vec{u} = (u_1, u_2) \in \mathcal{N}_b^*$, we see from (2.6) and (2.14) that $\int_{\Omega} u_1^2 u_2^2 dx \leq |u_1|_4^2 |u_2|_4^2 < 2$ and $||u_i||_{\lambda_i}^2 \geq S/\sqrt{2}$. Hence

$$\begin{split} &\mu_{2}|u_{2}|_{4}^{4}\|u_{1}\|_{\lambda_{1}}^{2}-\beta\|u_{2}\|_{\lambda_{2}}^{2}\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\geq\frac{\mu_{2}S}{2\sqrt{2}}-2b\beta_{0}\geq\frac{\mu_{2}S}{16};\\ &\mu_{1}|u_{1}|_{4}^{4}\|u_{2}\|_{\lambda_{2}}^{2}-\beta\|u_{1}\|_{\lambda_{1}}^{2}\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\geq\frac{\mu_{2}S}{16};\\ &\mu_{2}\|u_{1}\|_{\lambda_{1}}^{2}-\beta\|u_{2}\|_{\lambda_{2}}^{2}\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\geq\frac{\mu_{2}S}{16};\\ &\mu_{1}\|u_{2}\|_{\lambda_{2}}^{2}-\beta\|u_{1}\|_{\lambda_{1}}^{2}\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\geq\frac{\mu_{2}S}{16};\\ &\mu_{1}\|u_{2}\|_{\lambda_{2}}^{2}-\beta\|u_{1}\|_{\lambda_{1}}^{2}\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\geq\frac{\mu_{2}S}{16};\\ &\mu_{1}\mu_{2}-\beta^{2}\left(\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\right)^{2}\geq\frac{\mu_{2}^{2}S^{2}}{2^{8}}\cdot\frac{1}{\|u_{1}\|_{\lambda_{1}}^{2}\|u_{2}\|_{\lambda_{2}}^{2}}\geq\frac{\mu_{2}^{2}S^{2}}{2^{8}b^{2}};\\ &\mu_{1}\mu_{2}|u_{1}|_{4}^{4}|u_{2}|_{4}^{4}-\beta^{2}\left(\int_{\Omega}u_{1}^{2}u_{2}^{2}\,dx\right)^{2}\geq\frac{\mu_{2}^{2}S^{2}}{2^{8}b^{2}}. \end{split}$$

Then $\vec{u} \in \mathcal{M}_{\beta}^* \cap \mathcal{M}_{\beta}^{**}$. Moreover, combining these with (2.4) we have

$$t_i(\vec{u}) \ge \frac{\mu_2 S}{2^4} \cdot \frac{1}{\mu_1 \mu_2 |\mu_1|_4^4 |\mu_2|_4^4} \ge \frac{S}{2^6 \mu_1}, \ t_i(\vec{u}) \le \frac{2^9 b^3}{\mu_2^2 S^2} \mu_1, \ i = 1, 2.$$

This completes the proof.

Lemma 2.3. There exist $\beta_k \in (0, \beta_0]$ and $d_k > 0$ such that

$$\inf_{\vec{u}\in\partial\mathcal{N}_b} J_{\beta}(\vec{u}) \ge d_k > \sup_{\vec{u}\in\mathcal{N}_{\bar{b}}} J_{\beta}(\vec{u}), \quad \forall \, \beta \in (0, \beta_k).$$
 (2.15)

Proof. This proof is inspired by [25]. Define

$$I_i(u_i) := \frac{1}{4\mu_i} \|u_i\|_{\lambda_i}^4, \quad i = 1, 2.$$

Then for any $\vec{u} \in \overline{\mathcal{N}_b}$ and $\beta \in (0, \beta_0)$ we have

$$|J_{\beta}(\vec{u}) - I_{1}(u_{1}) - I_{2}(u_{2})|$$

$$= \frac{\beta \left| \beta \left(\int_{\Omega} u_{1}^{2} u_{2}^{2} dx \right)^{2} \sum_{i=1}^{2} \|u_{i}\|_{\lambda_{i}}^{4} / \mu_{i} - 2\|u_{1}\|_{\lambda_{1}}^{2} \|u_{2}\|_{\lambda_{2}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx \right|}{4[\mu_{1}\mu_{2} - \beta^{2} \left(\int_{\Omega} u_{1}^{2} u_{2}^{2} dx \right)^{2}]} \leq C\beta,$$

where C > 0 is independent of $\vec{u} \in \overline{\mathcal{N}_b}$ and $\beta \in (0, \beta_0)$. Therefore,

$$\sup_{\vec{u} \in \mathcal{N}_{\bar{b}}} J_{\beta}(\vec{u}) \leq \sup_{\vec{u} \in \mathcal{N}_{\bar{b}}} (I_{1}(u_{1}) + I_{2}(u_{2})) + C\beta \leq \frac{\bar{b}^{2}}{4\mu_{1}} + \frac{\bar{b}^{2}}{4\mu_{2}} + C\beta;$$

$$\inf_{\vec{u} \in \partial \mathcal{N}_{b}} J_{\beta}(\vec{u}) \geq \inf_{\vec{u} \in \partial \mathcal{N}_{b}} (I_{1}(u_{1}) + I_{2}(u_{2})) - C\beta \geq \frac{b^{2}}{4\mu_{1}} - C\beta.$$

Recalling (2.13), we let $\beta_k = \min\{\frac{\bar{b}^2}{8\mu_1 C}, \beta_0\}$ and $d_k = \frac{b^2}{4\mu_1} - C\beta_k$, then (2.15) holds. This completes the proof.

In the following we always let (i,j)=(1,2) or (i,j)=(2,1). Recalling (2.14) and Lemma 2.2, we can take β_k smaller if necessary such that, for any $\beta \in (0,\beta_k)$ and $\vec{u} \in \mathcal{N}_b^*$, there holds

$$||v||_{\lambda_i}^2 - \beta t_j(\vec{u}) \int_{\Omega} u_j^2 v^2 dx \ge \frac{1}{2} ||v||_{\lambda_i}^2, \quad \forall v \in H_0^1(\Omega), \ i = 1, 2.$$
 (2.16)

Clearly (2.16) implies that the operators $-\Delta + \lambda_i - \beta t_j(\vec{u})u_j^2$ are positive definite in $H_0^1(\Omega)$. In the rest of this section we fix any $\beta \in (0, \beta_k)$. We will show that (1.2) has at least k sign-changing solutions. For any $\vec{u} = (u_1, u_2) \in \mathcal{N}_b^*$, let $\tilde{w}_i \in H_0^1(\Omega)$ be the unique solution of the following linear problem

$$-\Delta \tilde{w}_i + \lambda_i \tilde{w}_i - \beta t_j(\vec{u}) u_i^2 \tilde{w}_i = \mu_i t_i(\vec{u}) u_i^3, \quad \tilde{w}_i \in H_0^1(\Omega). \tag{2.17}$$

Since $|u_i|_4^4 > 1/2$, so $\tilde{w}_i \neq 0$ and we see from (2.16) that

$$\int_{\Omega} u_i^3 \tilde{w}_i \, dx = \frac{1}{\mu_i t_i(\vec{u})} \left(\|\tilde{w}_i\|_{\lambda_i}^2 - \beta t_j(\vec{u}) \int_{\Omega} u_j^2 \tilde{w}_i^2 \, dx \right) \ge \frac{1}{2\mu_i t_i(\vec{u})} \|\tilde{w}_i\|_{\lambda_i}^2 > 0.$$

Define

$$w_i = \alpha_i \tilde{w}_i, \text{ where } \alpha_i = \frac{1}{\int_{\Omega} u_i^3 \tilde{w}_i \, dx} > 0.$$
 (2.18)

Then w_i is the unique solution of the following problem

$$\begin{cases}
-\Delta w_i + \lambda_i w_i - \beta t_j(\vec{u}) u_j^2 w_i = \alpha_i \mu_i t_i(\vec{u}) u_i^3, & w_i \in H_0^1(\Omega), \\
\int_{\Omega} u_i^3 w_i \, dx = 1.
\end{cases}$$
(2.19)

Now we define an operator $K = (K_1, K_2) : \mathcal{N}_b^* \to H$ by

$$K(\vec{u}) = (K_1(\vec{u}), K_2(\vec{u})) := \vec{w} = (w_1, w_2).$$
 (2.20)

Define the transformations

$$\sigma_i: H \to H$$
 by $\sigma_1(u_1, u_2) := (-u_1, u_2), \ \sigma_2(u_1, u_2) := (u_1, -u_2).$ (2.21)

Then it is easy to check that

$$K(\sigma_i(\vec{u})) = \sigma_i(K(\vec{u})), \quad i = 1, 2. \tag{2.22}$$

Lemma 2.4. $K \in C^1(\mathcal{N}_b^*, H)$.

Proof. It suffices to apply the Implicit Theorem to the C^1 map

$$\Psi: \mathcal{N}_h^* \times H_0^1(\Omega) \times \mathbb{R} \to H_0^1(\Omega) \times \mathbb{R}, \text{ where }$$

$$\Psi(\vec{u}, v, \alpha) = \left(v - (-\Delta + \lambda_i)^{-1} \left(\beta t_j(\vec{u}) u_j^2 v + \alpha \mu_i t_i(\vec{u}) u_i^3\right), \int_{\Omega} u_i^3 v \, dx - 1\right).$$

Note that (2.19) holds if and only if $\Psi(\vec{u}, w_i, \alpha_i) = (0, 0)$. By computing the derivative of Ψ with respect to (v, α) at the point (\vec{u}, w_i, α_i) in the direction $(\bar{w}, \bar{\alpha})$, we obtain a map $\Phi: H_0^1(\Omega) \times \mathbb{R} \to H_0^1(\Omega) \times \mathbb{R}$ given by

$$\begin{split} \Phi(\bar{w}, \bar{\alpha}) := & D_{v,\alpha} \Psi(\vec{u}, w_i, \alpha_i)(\bar{w}, \bar{\alpha}) \\ = & \left(\bar{w} - (-\Delta + \lambda_i)^{-1} \left(\beta t_j(\vec{u}) u_j^2 \bar{w} + \bar{\alpha} \mu_i t_i(\vec{u}) u_i^3 \right), \int_{\Omega} u_i^3 \bar{w} \, dx \right). \end{split}$$

Recalling (2.16), similarly as [10, Lemma 2.3] it is easy to prove that Φ is a bijective map. We omit the details.

Lemma 2.5. Assume that $\{\vec{u}_n = (u_{n,1}, u_{n,2}) : n \geq 1\} \subset \mathcal{N}_b$. Then there exists $\vec{w} \in H$ such that, up to a subsequence, $\vec{w}_n := K(\vec{u}_n) \to \vec{w}$ strongly in H.

Proof. Up to a subsequence, we may assume that $\vec{u}_n \to \vec{u} = (u_1, u_2)$ weakly in H and so $u_{n,i} \to u_i$ strongly in $L^4(\Omega)$, which implies $|u_i|_4 = 1$. Moreover, by Lemma 2.2 we may assume $t_i(\vec{u}_n) \to t_i > 0$. Recall that $w_{n,i} = \alpha_{n,i} \tilde{w}_{n,i}$, where $\alpha_{n,i}$ and $\tilde{w}_{n,i}$ are seen in (2.17)-(2.18). By (2.16)-(2.17) we have

$$\frac{1}{2} \|\tilde{w}_{n,i}\|_{\lambda_i}^2 \le \mu_i t_i(\vec{u}_n) \int_{\Omega} u_{n,i}^3 \tilde{w}_{n,i} \, dx \le C |\tilde{w}_{n,i}|_4 \le C \|\tilde{w}_{n,i}\|_{\lambda_i},$$

which implies that $\{\tilde{w}_{n,i}: n \geq 1\}$ are bounded in $H_0^1(\Omega)$. Up to a subsequence, we may assume that $\tilde{w}_{n,i} \to \tilde{w}_i$ weakly in $H_0^1(\Omega)$ and strongly in $L^4(\Omega)$. Then by (2.17) it is standard to prove that $\tilde{w}_{n,i} \to \tilde{w}_i$ strongly in $H_0^1(\Omega)$. Moreover, \tilde{w}_i satisfies $-\Delta \tilde{w}_i + \lambda_i \tilde{w}_i - \beta t_j u_j^2 \tilde{w}_i = \mu_i t_i u_i^3$. Since $|u_i|_4 = 1$, so $\tilde{w}_i \neq 0$ and then $\int_{\Omega} u_i^3 \tilde{w}_i dx > 0$, which implies that

$$\lim_{n \to \infty} \alpha_{n,i} = \lim_{n \to \infty} \frac{1}{\int_{\Omega} u_{n,i}^3 \tilde{w}_{n,i} dx} = \frac{1}{\int_{\Omega} u_i^3 \tilde{w}_i dx} =: \alpha_i.$$

Therefore,
$$w_{n,i} = \alpha_{n,i} \tilde{w}_{n,i} \to \alpha_i \tilde{w}_i =: w_i \text{ strongly in } H_0^1(\Omega).$$

To continue our proof, we need to use *vector genus* introduced by [26] to define proper minimax energy levels. Recall (2.7) and (2.21), as in [26] we consider the class of sets

$$\mathcal{F} = \{ A \subset \mathcal{M} : A \text{ is closed and } \sigma_i(\vec{u}) \in A \ \forall \vec{u} \in A, \ i = 1, 2 \},$$

and, for each $A \in \mathcal{F}$ and $k_1, k_2 \in \mathbb{N}$, the class of functions

$$F_{(k_1,k_2)}(A) = \left\{ f = (f_1, f_2) : A \to \prod_{i=1}^2 \mathbb{R}^{k_i - 1} : \begin{array}{l} f_i : A \to \mathbb{R}^{k_i - 1} \text{ continuous,} \\ f_i(\sigma_i(\vec{u})) = -f_i(\vec{u}) \text{ for each } i, \\ f_i(\sigma_j(\vec{u})) = f_i(\vec{u}) \text{ for } j \neq i \end{array} \right\}.$$

Here we denote $\mathbb{R}^0 := \{0\}$. Let us recall vector genus from [26].

Definition 2.1. (Vector genus, see [26]) Let $A \in \mathcal{F}$ and take any $k_1, k_2 \in \mathbb{N}$. We say that $\vec{\gamma}(A) \geq (k_1, k_2)$ if for every $f \in F_{(k_1, k_2)}(A)$ there exists $\vec{u} \in A$ such that $f(\vec{u}) = (f_1(\vec{u}), f_2(\vec{u})) = (0, 0)$. We denote

$$\Gamma^{(k_1,k_2)} := \{ A \in \mathcal{F} : \vec{\gamma}(A) \ge (k_1,k_2) \}.$$

Lemma 2.6. (see [26]) With the previous notations, the following properties hold.

- (i) Take $A_1 \times A_2 \subset \mathcal{M}$ and let $\eta_i : S^{k_i-1} := \{x \in \mathbb{R}^{k_i} : |x| = 1\} \to A_i$ be a homeomorphism such that $\eta_i(-x) = -\eta_i(x)$ for every $x \in S^{k_i-1}$, i = 1, 2. Then $A_1 \times A_2 \in \Gamma^{(k_1,k_2)}$.
- (ii) We have $\overline{\eta(A)} \in \Gamma^{(k_1,k_2)}$ whenever $A \in \Gamma^{(k_1,k_2)}$ and a continuous map $\eta: A \to \mathcal{M}$ is such that $\eta \circ \sigma_i = \sigma_i \circ \eta, \ \forall i = 1, 2$.

To obtain sign-changing solutions, as in many references such as [11, 4, 29], we should use cones of positive functions. Precisely, we define

$$\mathcal{P}_i := \{ \vec{u} = (u_1, u_2) \in H : u_i \ge 0 \}, \quad \mathcal{P} := \bigcup_{i=1}^2 (\mathcal{P}_i \cup -\mathcal{P}_i).$$
 (2.23)

Moreover, for $\delta > 0$ we define $\mathcal{P}_{\delta} := \{ \vec{u} \in H : \operatorname{dist}_{4}(\vec{u}, \mathcal{P}) < \delta \}$, where

$$\operatorname{dist}_{4}(\vec{u}, \mathcal{P}) := \min \left\{ \operatorname{dist}_{4}(u_{i}, \mathcal{P}_{i}), \operatorname{dist}_{4}(u_{i}, -\mathcal{P}_{i}), \quad i = 1, 2 \right\},$$

$$\operatorname{dist}_{4}(u_{i}, \pm \mathcal{P}_{i}) := \inf \left\{ |u_{i} - v|_{4} : v \in \pm \mathcal{P}_{i} \right\}.$$

$$(2.24)$$

Denote $u^{\pm} := \max\{0, \pm u\}$, then it is easy to check that $\operatorname{dist}_4(u_i, \pm \mathcal{P}_i) = |u_i^{\mp}|_4$. The following lemma was proved in [10].

Lemma 2.7. (see [10, Lemma 2.6]) Let $k_1, k_2 \geq 2$. Then for any $\delta < 2^{-1/4}$ and any $A \in \Gamma^{(k_1,k_2)}$ there holds $A \setminus \mathcal{P}_{\delta} \neq \emptyset$.

Lemma 2.8. There exists $A \in \Gamma^{(k+1,k+1)}$ such that $A \subset \mathcal{N}_b$ and $\sup_A J_\beta < d_k$.

Proof. Recalling W_{k+1} in (2.12), we define

$$A_1 = A_2 := \{ u \in W_{k+1} : |u|_4 = 1 \}.$$

Note that there exists an obvious odd homeomorphism from S^k to A_i . By Lemma 2.6-(i) one has $A:=A_1\times A_2\in \Gamma^{(k+1,k+1)}$. We see from (2.12) that $A\subset \mathcal{N}_{\bar{b}}$, and so Lemma 2.3 yields $\sup_A J_{\beta} < d_k$.

For every $k_1, k_2 \in [2, k+1]$ and $0 < \delta < 2^{-1/4}$, we define

$$c_{\beta,\delta}^{k_1,k_2} := \inf_{A \in \Gamma_{\alpha}^{(k_1,k_2)}} \sup_{\vec{u} \in A \setminus \mathcal{P}_{\delta}} J_{\beta}(\vec{u}), \tag{2.25}$$

where

$$\Gamma_{\beta}^{(k_1, k_2)} := \left\{ A \in \Gamma^{(k_1, k_2)} : A \subset \mathcal{N}_b, \sup_{A} J_{\beta} < d_k \right\}.$$
(2.26)

Noting that $\Gamma_{\beta}^{(\tilde{k}_1,\tilde{k}_2)} \subset \Gamma_{\beta}^{(k_1,k_2)}$ for any $\tilde{k}_1 \geq k_1$ and $\tilde{k}_2 \geq k_2$, we see that Lemma 2.8 yields $\Gamma_{\beta}^{(k_1,k_2)} \neq \emptyset$ and so $c_{\beta,\delta}^{k_1,k_2}$ is well defined for any $k_1,k_2 \in [2,k+1]$. Moreover,

$$c_{\beta,\delta}^{k_1,k_2} < d_k$$
 for every $\delta \in (0,2^{-1/4})$ and $k_1,k_2 \in [2,k+1]$.

We will prove that $c_{\beta,\delta}^{k_1,k_2}$ is a critical value of E_{β} for $\delta > 0$ sufficiently small. Define $\mathcal{N}_{b,\beta} := \{\vec{u} \in \mathcal{N}_b : J_{\beta}(\vec{u}) < d_k\}$, then Lemma 2.3 yields $\mathcal{N}_{\bar{b}} \subset \mathcal{N}_{b,\beta}$.

Lemma 2.9. For any sufficiently small $\delta \in (0, 2^{-1/4})$, there holds

$$dist_4(K(\vec{u}), \mathcal{P}) < \delta/2, \quad \forall \vec{u} \in \mathcal{N}_{b,\beta}, \ dist_4(\vec{u}, \mathcal{P}) < \delta.$$

Proof. Assume by contradiction that there exist $\delta_n \to 0$ and $\vec{u}_n = (u_{n,1}, u_{n,2}) \in \mathcal{N}_{b,\beta}$ such that $\mathrm{dist}_4(\vec{u}_n, \mathcal{P}) < \delta_n$ and $\mathrm{dist}_4(K(\vec{u}_n), \mathcal{P}) \geq \delta_n/2$. Without loss of generality we may assume that $\mathrm{dist}_4(\vec{u}_n, \mathcal{P}) = \mathrm{dist}_4(u_{n,1}, \mathcal{P}_1)$. Write $K(\vec{u}_n) = \vec{w}_n = (w_{n,1}, w_{n,2})$ and $w_{n,i} = \alpha_{n,i} \tilde{w}_{n,i}$ as in Lemma 2.5. Then by the proof of Lemma 2.5, we see that $\alpha_{n,i}$ are all uniformly bounded. Combining this with (2.16) and (2.19), we deduce that

$$\begin{aligned} \operatorname{dist}_{4}(w_{n,1},\mathcal{P}_{1})|w_{n,1}^{-}|_{4} &= |w_{n,1}^{-}|_{4}^{2} \leq C||w_{n,1}^{-}||_{\lambda_{1}}^{2} \\ &\leq C \int_{\Omega} \left(|\nabla w_{n,1}^{-}|^{2} + \lambda_{1}(w_{n,1}^{-})^{2} - \beta t_{2}(\vec{u}_{n})u_{n,2}^{2}(w_{n,1}^{-})^{2} \right) \, dx \\ &= -C\alpha_{n,1}\mu_{1}t_{1}(\vec{u}_{n}) \int_{\Omega} u_{n,1}^{3}w_{n,1}^{-} \, dx \\ &\leq C \int_{\Omega} (u_{n,1}^{-})^{3}w_{n,1}^{-} \, dx \leq C|u_{n,1}^{-}|_{4}^{3}|w_{n,1}^{-}|_{4} \\ &= C \operatorname{dist}_{4}(u_{n,1},\mathcal{P}_{1})^{3}|w_{n,1}^{-}|_{4} \leq C\delta_{n}^{3}|w_{n,1}^{-}|_{4}. \end{aligned}$$

So $\operatorname{dist}_4(K(\vec{u}_n), \mathcal{P}) \leq \operatorname{dist}_4(w_{n,1}, \mathcal{P}_1) \leq C\delta_n^3 < \delta_n/2$ holds for n sufficiently large, which is a contradiction. This completes the proof.

Now let us define a map $V: \mathcal{N}_b^* \to H$ by $V(\vec{u}) := \vec{u} - K(\vec{u})$. We will prove that $(\sqrt{t_1(\vec{u})}u_1, \sqrt{t_2(\vec{u})}u_2)$ is a sign-changing solution of (1.2) if $\vec{u} = (u_1, u_2) \in \mathcal{N}_b \setminus \mathcal{P}$ satisfies $V(\vec{u}) = 0$.

Lemma 2.10. Let $\vec{u}_n = (u_{n,1}, u_{n,2}) \in \mathcal{N}_b$ be such that

$$J_{\beta}(\vec{u}_n) \to c < d_k \quad and \quad V(\vec{u}_n) \to 0 \quad strongly \ in \ H.$$

Then up to a subsequence, there exists $\vec{u} \in \mathcal{N}_b$ such that $\vec{u}_n \to \vec{u}$ strongly in H and $V(\vec{u}) = 0$.

Proof. By Lemma 2.5, up to a subsequence, we may assume that $\vec{u}_n \to \vec{u} = (u_1, u_2)$ weakly in H and $\vec{w}_n := K(\vec{u}_n) = (w_{n,1}, w_{n,2}) \to \vec{w} = (w_1, w_2)$ strongly in H. Recalling $V(\vec{u}_n) \to 0$, we get

$$\int_{\Omega} \nabla u_{n,i} \nabla (u_{n,i} - u_i) \, dx = \int_{\Omega} \nabla (w_{n,i} - w_i) \nabla (u_{n,i} - u_i) \, dx$$
$$+ \int_{\Omega} \nabla w_i \nabla (u_{n,i} - u_i) \, dx + \int_{\Omega} \nabla (u_{n,i} - w_{n,i}) \nabla (u_{n,i} - u_i) \, dx = o(1).$$

Then it is easy to see that $\vec{u}_n \to \vec{u}$ strongly in H and so $\vec{u} \in \overline{\mathcal{N}_b}$. Hence $V(\vec{u}) = \lim_{n \to \infty} V(\vec{u}_n) = 0$. Moreover, $J_{\beta}(\vec{u}) = c < d_k$ and so $\vec{u} \in \mathcal{N}_b$.

Lemma 2.11. Recall $C_0 > 0$ in Lemma 2.2. Then

$$J'_{\beta}(\vec{u})[V(\vec{u})] \ge \frac{C_0}{2} ||V(\vec{u})||_H^2, \text{ for any } \vec{u} \in \mathcal{N}_b.$$

Proof. Fix any $\vec{u} = (u_1, u_2) \in \mathcal{N}_b$ and write $\vec{w} = K(\vec{u}) = (w_1, w_2)$ as above, then $V(\vec{u}) = (u_1 - w_1, u_2 - w_2)$. By (2.19) we have $\int_{\Omega} u_i^3(u_i - w_i) dx = 1 - 1 = 0$. Then we deduce from (2.8)-(2.9), (2.16) and (2.19) that

$$\begin{split} J_{\beta}'(\vec{u})[V(\vec{u})] \\ &= \sum_{i=1}^{2} t_{i}(\vec{u}) \int_{\Omega} \left(\nabla u_{i} \nabla (u_{i} - w_{i}) + \lambda_{i} u_{i}(u_{i} - w_{i}) - t_{j}(\vec{u}) \beta u_{i}(u_{i} - w_{i}) u_{j}^{2} \right) \, dx \\ &= \sum_{i=1}^{2} t_{i}(\vec{u}) \int_{\Omega} \left(\nabla u_{i} \nabla (u_{i} - w_{i}) + \lambda_{i} u_{i}(u_{i} - w_{i}) - t_{j}(\vec{u}) \beta w_{i}(u_{i} - w_{i}) u_{j}^{2} \right. \\ &\qquad \left. - t_{j}(\vec{u}) \beta (u_{i} - w_{i})^{2} u_{j}^{2} \right) dx \\ &= \sum_{i=1}^{2} t_{i}(\vec{u}) \int_{\Omega} \left(\nabla u_{i} \nabla (u_{i} - w_{i}) + \lambda_{i} u_{i}(u_{i} - w_{i}) - \nabla w_{i} \nabla (u_{i} - w_{i}) - \lambda_{i} w_{i}(u_{i} - w_{i}) + \alpha_{i} \mu_{i} t_{i}(\vec{u}) u_{i}^{3}(u_{i} - w_{i}) - t_{j}(\vec{u}) \beta (u_{i} - w_{i})^{2} u_{j}^{2} \right) dx \end{split}$$

$$= \sum_{i=1}^{2} t_{i}(\vec{u}) \int_{\Omega} \left(|\nabla(u_{i} - w_{i})|^{2} + \lambda_{i} |u_{i} - w_{i}|^{2} - t_{j}(\vec{u}) \beta(u_{i} - w_{i})^{2} u_{j}^{2} \right) dx$$

$$\geq \sum_{i=1}^{2} \frac{t_{i}(\vec{u})}{2} ||u_{i} - w_{i}||_{\lambda_{i}}^{2} \geq \frac{C_{0}}{2} ||V(\vec{u})||_{H}^{2}.$$

This completes the proof.

Lemma 2.12. There exists a unique global solution $\eta = (\eta_1, \eta_2) : [0, \infty) \times \mathcal{N}_{b,\beta} \to H$ for the initial value problem

$$\frac{d}{dt}\eta(t,\vec{u}) = -V(\eta(t,\vec{u})), \quad \eta(0,\vec{u}) = \vec{u} \in \mathcal{N}_{b,\beta}. \tag{2.27}$$

Moreover,

- (i) $\eta(t, \vec{u}) \in \mathcal{N}_{b,\beta}$ for any t > 0 and $\vec{u} \in \mathcal{N}_{b,\beta}$.
- (ii) $\eta(t, \sigma_i(\vec{u})) = \sigma_i(\eta(t, \vec{u}))$ for any t > 0, $\vec{u} \in \mathcal{N}_{b,\beta}$ and i = 1, 2.
- (iii) For every $\vec{u} \in \mathcal{N}_{b,\beta}$, the map $t \mapsto J_{\beta}(\eta(t,\vec{u}))$ is non-increasing.
- (iv) There exists $\delta_0 \in (0, 2^{-1/4})$ such that, for every $\delta < \delta_0$, there holds

$$\eta(t, \vec{u}) \in \mathcal{P}_{\delta}$$
 whenever $\vec{u} \in \mathcal{N}_{b,\beta} \cap \mathcal{P}_{\delta}$ and $t > 0$.

Proof. Recalling Lemma 2.4, we have $V(\vec{u}) \in C^1(\mathcal{N}_b^*, H)$. Since $\mathcal{N}_{b,\beta} \subset \mathcal{N}_b^*$ and \mathcal{N}_b^* is open, so (2.27) has a unique solution $\eta : [0, T_{\text{max}}) \times \mathcal{N}_{b,\beta} \to H$, where $T_{\text{max}} > 0$ is the maximal time such that $\eta(t, \vec{u}) \in \mathcal{N}_b^*$ for all $t \in [0, T_{\text{max}})$ (Note that $V(\cdot)$ is defined only on \mathcal{N}_b^*). We should prove $T_{\text{max}} = +\infty$ for any $\vec{u} \in \mathcal{N}_{b,\beta}$. Fixing any $\vec{u} = (u_1, u_2) \in \mathcal{N}_{b,\beta}$, we have

$$\frac{d}{dt} \int_{\Omega} \eta_i(t, \vec{u})^4 dx = -4 \int_{\Omega} \eta_i(t, \vec{u})^3 (\eta_i(t, \vec{u}) - K_i(\eta(t, \vec{u}))) dx
= 4 - 4 \int_{\Omega} \eta_i(t, \vec{u})^4 dx, \quad \forall 0 < t < T_{\text{max}}.$$

Recalling $\int_{\Omega} \eta_i(0, \vec{u})^4 dx = \int_{\Omega} u_i^4 dx = 1$, we deduce that $\int_{\Omega} \eta_i(t, \vec{u})^4 dx \equiv 1$ for all $0 \le t < T_{\text{max}}$. So $\eta(t, \vec{u}) \in \mathcal{M}$, that is $\eta(t, \vec{u}) \in \mathcal{M} \cap \mathcal{N}_b^* = \mathcal{N}_b$ for all $t \in [0, T_{\text{max}})$. Assume by contradiction that $T_{\text{max}} < +\infty$, then $\eta(T_{\text{max}}, \vec{u}) \in \partial \mathcal{N}_b$, and so $J_{\beta}(\eta(T_{\text{max}}, \vec{u})) \ge d_k$. Since $\eta(t, \vec{u}) \in \mathcal{N}_b$ for any $t \in [0, T_{\text{max}})$, we deduce from Lemma 2.11 that

$$J_{\beta}(\eta(T_{\max}, \vec{u})) = J_{\beta}(\vec{u}) - \int_{0}^{T_{\max}} J_{\beta}'(\eta(t, \vec{u}))[V(\eta(t, \vec{u}))] dt$$

$$\leq J_{\beta}(\vec{u}) - \frac{C_{0}}{2} \int_{0}^{T_{\max}} \|V(\eta(t, \vec{u}))\|_{H}^{2} dt \leq J_{\beta}(\vec{u}) < d_{k},$$
(2.28)

a contradiction. So $T_{\max} = +\infty$. Then similarly as (2.28) we have $J_{\beta}(\eta(t, \vec{u})) \leq J_{\beta}(\vec{u}) < d_k$ for all t > 0, so $\eta(t, \vec{u}) \in \mathcal{N}_{b,\beta}$ and then (i), (iii) hold.

By (2.22) we have $V(\sigma_i(\vec{u})) = \sigma_i(V(\vec{u}))$. Then by the uniqueness of solutions of the initial value problem (2.27), it is easy to check that (ii) holds.

Finally, let $\delta_0 \in (0, 2^{-1/4})$ such that Lemma 2.9 holds for every $\delta < \delta_0$. For any $\vec{u} \in \mathcal{N}_{b,\beta}$ with $\operatorname{dist}_4(\vec{u}, \mathcal{P}) = \delta < \delta_0$, since

$$\eta(t, \vec{u}) = \vec{u} + t \frac{d}{dt} \eta(0, \vec{u}) + o(t) = \vec{u} - tV(\vec{u}) + o(t) = (1 - t)\vec{u} + tK(\vec{u}) + o(t),$$

so we see from Lemma 2.9 that

$$\begin{aligned} \operatorname{dist}_{4}(\eta(t, \vec{u}), \mathcal{P}) &= \operatorname{dist}_{4}((1 - t)\vec{u} + tK(\vec{u}) + o(t), \mathcal{P}) \\ &\leq (1 - t)\operatorname{dist}_{4}(\vec{u}, \mathcal{P}) + t\operatorname{dist}_{4}(K(\vec{u}), \mathcal{P}) + o(t) \\ &\leq (1 - t)\delta + t\delta/2 + o(t) < \delta \end{aligned}$$

for t > 0 sufficiently small. Hence (iv) holds.

Proof of Theorem 1.1.

Step 1. Fix any $k_1, k_2 \in [2, k+1]$ and take any $\delta \in (0, \delta_0)$. We prove that (1.2) has a sign-changing solution $(\tilde{u}_1, \tilde{u}_2) \in H$ such that $E_{\beta}(\tilde{u}_1, \tilde{u}_2) = c_{\beta, \delta}^{k_1, k_2}$.

Write $c_{\beta,\delta}^{k_1,k_2}$ simply by c in this step. Recall that $c < d_k$. We claim that there exists a sequence $\{\vec{u}_n : n \geq 1\} \subset \mathcal{N}_{b,\beta}$ such that

$$J_{\beta}(\vec{u}_n) \to c, \ V(\vec{u}_n) \to 0 \text{ as } n \to \infty, \text{ and } \operatorname{dist}_4(\vec{u}_n, \mathcal{P}) \ge \delta, \ \forall n \in \mathbb{N}.$$
 (2.29)

If (2.29) does not hold, there exists small $\varepsilon \in (0,1)$ such that

$$||V(\vec{u})||_H^2 \ge \varepsilon$$
, $\forall u \in \mathcal{N}_{b,\beta}$, $|J_{\beta}(\vec{u}) - c| \le 2\varepsilon$, $\operatorname{dist}_4(\vec{u}, \mathcal{P}) \ge \delta$.

Recalling the definition of c in (2.25), we see that there exists $A \in \Gamma_{\beta}^{(k_1,k_2)}$ such that

$$\sup_{A \setminus \mathcal{P}_{\delta}} J_{\beta} < c + \varepsilon.$$

Since $\sup_A J_{\beta} < d_k$, so $A \subset \mathcal{N}_{b,\beta}$. Then we can consider $B = \eta(4/C_0, A)$, where η is in Lemma 2.12 and C_0 is in Lemma 2.2. Lemma 2.12-(i) yields $B \subset \mathcal{N}_{b,\beta}$. By Lemma 2.6-(ii) and Lemma 2.12-(ii) we have $B \in \Gamma^{(k_1,k_2)}$. Again by Lemma 2.12-(iii), we have $\sup_B J_{\beta} \leq \sup_A J_{\beta} < d_k$, that is $B \in \Gamma_{\beta}^{(k_1,k_2)}$ and so $\sup_{B \setminus \mathcal{P}_{\delta}} J_{\beta} \geq c$. Then by Lemma 2.7 we can take $\vec{u} \in A$ such that $\eta(4/C_0, \vec{u}) \in B \setminus \mathcal{P}_{\delta}$ and

$$c - \varepsilon \le \sup_{\beta \setminus \mathcal{P}_{\delta}} J_{\beta} - \varepsilon < J_{\beta}(\eta(4/C_0, \vec{u})).$$

Since $\eta(t, \vec{u}) \in \mathcal{N}_{b,\beta}$ for any $t \geq 0$, Lemma 2.12-(iv) yields $\eta(t, \vec{u}) \notin \mathcal{P}_{\delta}$ for any $t \in [0, 4/C_0]$. In particular, $\vec{u} \notin \mathcal{P}_{\delta}$ and so $J_{\beta}(\vec{u}) < c + \varepsilon$. Then for any $t \in [0, 4/C_0]$, we have

$$c - \varepsilon < J_{\beta}(\eta(4/C_0, \vec{u})) < J_{\beta}(\eta(t, \vec{u})) < J_{\beta}(\vec{u}) < c + \varepsilon,$$

which implies $||V(\eta(t, \vec{u}))||_H^2 \ge \varepsilon$ and

$$\frac{d}{dt}J_{\beta}(\eta(t,\vec{u})) = -J_{\beta}'(\eta(t,\vec{u}))[V(\eta(t,\vec{u}))] \le -\frac{C_0}{2}\|V(\eta(t,\vec{u}))\|_H^2 \le -\frac{C_0}{2}\varepsilon$$

for every $t \in [0, 4/C_0]$. Hence,

$$c - \varepsilon < J_{\beta}(\eta(4/C_0, \vec{u})) \le J_{\beta}(\vec{u}) - \int_0^{4/C_0} \frac{C_0}{2} \varepsilon \, dt < c + \varepsilon - 2\varepsilon = c - \varepsilon,$$

a contradiction. Therefore (2.29) holds. By Lemma 2.10, up to a subsequence, there exists $\vec{u} = (u_1, u_2) \in \mathcal{N}_{b,\beta}$ such that $\vec{u}_n \to \vec{u}$ strongly in H and $V(\vec{u}) = 0$, $J_{\beta}(\vec{u}) = c = c_{\beta,\delta}^{k_1,k_2}$. Since $\mathrm{dist}_4(\vec{u}_n,\mathcal{P}) \geq \delta$, so $\mathrm{dist}_4(\vec{u},\mathcal{P}) \geq \delta$, which implies that both u_1 and u_2 are sign-changing. Since $V(\vec{u}) = 0$, so $\vec{u} = K(\vec{u})$. Combining this with (2.19)-(2.20), we see that \vec{u} satisfies

$$\begin{cases}
-\Delta u_1 + \lambda_1 u_1 = \alpha_1 \mu_1 t_1(\vec{u}) u_1^3 + \beta t_2(\vec{u}) u_2^2 u_1, \\
-\Delta u_2 + \lambda_2 u_2 = \alpha_2 \mu_2 t_2(\vec{u}) u_2^3 + \beta t_1(\vec{u}) u_1^2 u_2.
\end{cases}$$
(2.30)

Recall that $|u_i|_4 = 1$ and $t_i(\vec{u})$ satisfies (2.4). Multiplying (2.30) by u_i and integrating over Ω , we obtain that $\alpha_1 = \alpha_2 = 1$. Again by (2.30), we see that $(\tilde{u}_1, \tilde{u}_2) := (\sqrt{t_1(\vec{u})}u_1, \sqrt{t_2(\vec{u})}u_2)$ is a sign-changing solution of the original problem (1.2). Moreover, (2.5) and (2.10) yield $E_{\beta}(\tilde{u}_1, \tilde{u}_2) = J_{\beta}(u_1, u_2) = c_{\beta}^{k_1, k_2}$.

Step 2. We prove that (1.2) has at least k sign-changing solutions.

Assume by contradiction that (1.2) has at most k-1 sign-changing solutions. Fix any $k_2 \in [2, k+1]$ and $\delta \in (0, \delta_0)$. Since $\Gamma_{\beta}^{(k_1+1, k_2)} \subset \Gamma_{\beta}^{(k_1, k_2)}$, we have

$$c_{\beta,\delta}^{2,k_2} \le c_{\beta,\delta}^{3,k_2} \le \dots \le c_{\beta,\delta}^{k,k_2} \le c_{\beta,\delta}^{k+1,k_2} < d_k.$$
 (2.31)

Since $c_{\beta,\delta}^{k_1,k_2}$ is a sign-changing critical value of E_{β} for each $k_1 \in [2, k+1]$ (that is, E_{β} has a sign-changing critical point \vec{u} with $E_{\beta}(\vec{u}) = c_{\beta,\delta}^{k_1,k_2}$), by (2.31) and our assumption that (1.2) has at most k-1 sign-changing solutions, there exists some $2 \le N_1 \le k$ such that

$$c_{\beta,\delta}^{N_1,k_2} = c_{\beta,\delta}^{N_1+1,k_2} =: \bar{c} < d_k.$$
 (2.32)

Define

$$\mathcal{K} := \{ \vec{u} \in \mathcal{N}_b : \vec{u} \text{ sign-changing}, \ J_{\beta}(\vec{u}) = \bar{c}, \ V(\vec{u}) = 0 \}.$$
 (2.33)

Then \mathcal{K} is finite. By (2.22) one has that $\sigma_i(\vec{u}) \in \mathcal{K}$ if $\vec{u} \in \mathcal{K}$, that is, $\mathcal{K} \subset \mathcal{F}$. Hence there exist $k_0 \leq k-1$ and $\{\vec{u}_m : 1 \leq m \leq k_0\} \subset \mathcal{K}$ such that

$$\mathcal{K} = \{ \vec{u}_m, \, \sigma_1(\vec{u}_m), \, \sigma_2(\vec{u}_m), \, -\vec{u}_m : 1 \le m \le k_0 \}.$$

Then there exist open neighborhoods $O_{\vec{u}_m}$ of \vec{u}_m in H, such that any two of $\overline{O_{\vec{u}_m}}$, $\sigma_1(\overline{O_{\vec{u}_m}})$, $\sigma_2(\overline{O_{\vec{u}_m}})$ and $-\overline{O_{\vec{u}_m}}$, where $1 \leq m \leq k_0$, are disjointed and

$$\mathcal{K} \subset O := \bigcup_{m=1}^{k_0} O_{\vec{u}_m} \cup \sigma_1(O_{\vec{u}_m}) \cup \sigma_2(O_{\vec{u}_m}) \cup -O_{\vec{u}_m}.$$

Define a continuous map $\tilde{f}: \overline{O} \to \mathbb{R} \setminus \{0\}$ by

$$\tilde{f}(\vec{u}) := \begin{cases} 1, & \text{if } \vec{u} \in \bigcup_{m=1}^{k_0} \overline{O_{\vec{u}_m}} \cup \sigma_2(\overline{O_{\vec{u}_m}}), \\ -1, & \text{if } \vec{u} \in \bigcup_{m=1}^{k_0} \sigma_1(\overline{O_{\vec{u}_m}}) \cup -\overline{O_{\vec{u}_m}}. \end{cases}$$

Then $\tilde{f}(\sigma_1(\vec{u})) = -\tilde{f}(\vec{u})$ and $\tilde{f}(\sigma_2(\vec{u})) = \tilde{f}(\vec{u})$. By Tietze's extension theorem, there exists $f \in C(H, \mathbb{R})$ such that $f|_{\mathcal{O}} \equiv \tilde{f}$. Define

$$F(\vec{u}) := \frac{f(\vec{u}) + f(\sigma_2(\vec{u})) - f(\sigma_1(\vec{u})) - f(-\vec{u})}{4},$$

then $F|_O \equiv \tilde{f}$, $F(\sigma_1(\vec{u})) = -F(\vec{u})$ and $F(\sigma_2(\vec{u})) = F(\vec{u})$. Define

$$\mathcal{K}_{\tau} := \left\{ \vec{u} \in \mathcal{N}_b : \inf_{\vec{v} \in \mathcal{K}} \|\vec{u} - \vec{v}\|_H < \tau \right\}.$$

Then we can take small $\tau > 0$ such that $\mathcal{K}_{2\tau} \subset O$. Recalling $V(\vec{u}) = 0$ in \mathcal{K} and \mathcal{K} finite, we see that there exists $\widetilde{C} > 0$ such that

$$||V(\vec{u})||_H \le \widetilde{C}, \quad \forall \ \vec{u} \in \overline{\mathcal{K}_{2\tau}}.$$
 (2.34)

For any $\vec{u} \in \mathcal{K}_{2\tau}$, we have $F(\vec{u}) = \tilde{f}(\vec{u}) \neq 0$. That is $F(\mathcal{K}_{2\tau}) \subset \mathbb{R} \setminus \{0\}$. By (2.33) and Lemma 2.10 there exists small $\varepsilon \in (0, (d_k - \bar{c})/2)$ such that

$$||V(\vec{u})||_H^2 \ge \varepsilon, \quad \forall u \in \mathcal{N}_b \setminus (\mathcal{K}_\tau \cup \mathcal{P}_\delta) \text{ satisfying } |J_\beta(\vec{u}) - \bar{c}| \le 2\varepsilon.$$
 (2.35)

Recalling C_0 in Lemma 2.2, we let

$$\alpha := \frac{1}{2} \min \left\{ 1, \frac{\tau C_0}{2\tilde{C}} \right\}. \tag{2.36}$$

By (2.25)-(2.26) and (2.32) we take $A \in \Gamma_{\beta}^{(N_1+1,k_2)}$ such that

$$\sup_{A \setminus \mathcal{P}_{\delta}} J_{\beta} < c_{\beta,\delta}^{N_1 + 1, k_2} + \alpha \varepsilon / 2 = \bar{c} + \alpha \varepsilon / 2. \tag{2.37}$$

Let $B:=A\setminus \mathcal{K}_{2\tau}$, then it is easy to check that $B\subset \mathcal{F}$. We claim that $\vec{\gamma}(B)\geq (N_1,k_2)$. If not, there exists $\tilde{g}\in F_{(N_1,k_2)}(B)$ such that $\tilde{g}(\vec{u})\neq 0$ for any $\vec{u}\in B$. By Tietze's extension theorem, there exists $\bar{g}=(\bar{g}_1,\bar{g}_2)\in C(H,\mathbb{R}^{N_1-1}\times\mathbb{R}^{k_2-1})$ such that $\bar{g}|_B\equiv \tilde{g}$. Define $g=(g_1,g_2)\in C(H,\mathbb{R}^{N_1-1}\times\mathbb{R}^{k_2-1})$ by

$$g_1(\vec{u}) := \frac{\bar{g}_1(\vec{u}) + \bar{g}_1(\sigma_2(\vec{u})) - \bar{g}_1(\sigma_1(\vec{u})) - \bar{g}_1(-\vec{u})}{4},$$

$$g_2(\vec{u}) := \frac{\bar{g}_2(\vec{u}) + \bar{g}_2(\sigma_1(\vec{u})) - \bar{g}_2(\sigma_2(\vec{u})) - \bar{g}_2(-\vec{u})}{4},$$

then $g|_B \equiv \tilde{g}$, $g_i(\sigma_i(\vec{u})) = -g_i(\vec{u})$ and $g_i(\sigma_j(\vec{u})) = g_i(\vec{u})$ for $j \neq i$. Finally we define $G = (G_1, G_2) \in C(A, \mathbb{R}^{N_1 + 1 - 1} \times \mathbb{R}^{k_2 - 1})$ by

$$G_1(\vec{u}) := (F(\vec{u}), g_1(\vec{u})) \in \mathbb{R}^{N_1 + 1 - 1}, \quad G_2(\vec{u}) := g_2(\vec{u}) \in \mathbb{R}^{k_2 - 1}.$$

By our constructions of F and g, we have $G \in F_{(N_1+1,k_2)}(A)$. Since $\vec{\gamma}(A) \geq (N_1+1,k_2)$, so $G(\vec{u})=0$ for some $\vec{u}\in A$. If $\vec{u}\in \mathcal{K}_{2\tau}$, then $F(\vec{u})\neq 0$, a contradiction. So $\vec{u}\in A\setminus \mathcal{K}_{2\tau}=B$, and then $g(\vec{u})=\tilde{g}(\vec{u})\neq 0$, also a contradiction. Hence $\vec{\gamma}(B)\geq (N_1,k_2)$. Note that $B\subset A\subset \mathcal{N}_b$ and $\sup_B J_\beta\leq \sup_A J_\beta < d_k$, we see that $B\subset \mathcal{N}_{b,\beta}$ and $B\in \Gamma_\beta^{(N_1,k_2)}$. Then we can consider $D:=\eta(\tau/(2\widetilde{C}),B)$, where η is in Lemma 2.12 and \widetilde{C} is in (2.34). By Lemma 2.6-(ii) and Lemma 2.12 we have $D\subset \mathcal{N}_{b,\beta}$, $D\in \Gamma^{(N_1,k_2)}$ and $\sup_D J_\beta\leq \sup_B J_\beta < d_k$, that is $D\in \Gamma_\beta^{(N_1,k_2)}$. Then we see from (2.25)-(2.26) and (2.32) that

$$\sup_{D \setminus \mathcal{P}_{\delta}} J_{\beta} \ge c_{\beta,\delta}^{N_1,k_2} = \bar{c}.$$

By Lemma 2.7 we can take $\vec{u} \in B$ such that $\eta(\tau/(2\tilde{C}), \vec{u}) \in D \setminus \mathcal{P}_{\delta}$ and

$$\bar{c} - \alpha \varepsilon / 2 \le \sup_{D \setminus \mathcal{P}_{\delta}} J_{\beta} - \alpha \varepsilon / 2 < J_{\beta}(\eta(\tau / (2\widetilde{C}), \vec{u})).$$

Since $\eta(t, \vec{u}) \in \mathcal{N}_{b,\beta}$ for any $t \geq 0$, Lemma 2.12-(iv) yields $\eta(t, \vec{u}) \notin \mathcal{P}_{\delta}$ for any $t \in [0, \tau/(2\tilde{C})]$. In particular, $\vec{u} \notin \mathcal{P}_{\delta}$ and so (2.37) yields $J_{\beta}(\vec{u}) < \bar{c} + \alpha \varepsilon/2$. Then for any $t \in [0, \tau/(2\tilde{C})]$, we have

$$\bar{c} - \alpha \varepsilon/2 < J_{\beta}(\eta(\tau/(2\tilde{C}), \vec{u})) \le J_{\beta}(\eta(t, \vec{u})) \le J_{\beta}(\vec{u}) < \bar{c} + \alpha \varepsilon/2.$$

Recall that $\vec{u} \in B = A \setminus \mathcal{K}_{2\tau}$. If there exists $T \in (0, \tau/(2\tilde{C}))$ such that $\eta(T, \vec{u}) \in \mathcal{K}_{\tau}$, then there exist $0 \le t_1 < t_2 \le T$ such that $\eta(t_1, \vec{u}) \in \partial \mathcal{K}_{2\tau}$, $\eta(t_2, \vec{u}) \in \partial \mathcal{K}_{\tau}$ and $\eta(t, \vec{u}) \in \mathcal{K}_{2\tau} \setminus \mathcal{K}_{\tau}$ for any $t \in (t_1, t_2)$. So we see from (2.34) that

$$\tau \le \|\eta(t_1, \vec{u}) - \eta(t_2, \vec{u})\|_H = \left\| \int_{t_1}^{t_2} V(\eta(t, \vec{u})) dt \right\|_H \le 2\widetilde{C}(t_2 - t_1),$$

that is, $\tau/(2\widetilde{C}) \leq t_2 - t_1 \leq T$, a contradiction. Hence $\eta(t, \vec{u}) \notin \mathcal{K}_{\tau}$ for any $t \in (0, \tau/(2\widetilde{C}))$. Then as Step 1, we deduce from (2.35) and (2.36) that

$$\bar{c} - \frac{\alpha \varepsilon}{2} < J_{\beta}(\eta(\tau/(2\widetilde{C}), \vec{u})) \le J_{\beta}(\vec{u}) - \int_{0}^{\frac{\tau}{2\widetilde{C}}} \frac{C_{0}}{2} \varepsilon \, dt < \bar{c} + \frac{\alpha \varepsilon}{2} - \alpha \varepsilon = \bar{c} - \frac{\alpha \varepsilon}{2},$$

a contradiction. Hence (1.2) has at least k sign-changing solutions for any $\beta \in (0, \beta_k)$. This completes the proof.

3 Proof of Theorem 1.2

Let k=1 in Section 2. By the proof of Theorem 1.1 there exists $\beta_1 > 0$ such that, for any $\beta \in (0, \beta_1)$, (1.2) has a sign-changing solution $(u_{\beta,1}, v_{\beta,1})$ with $E_{\beta}(u_{\beta,1}, v_{\beta,1}) = c_{\beta,\delta}^{2,2} < d_1$. Recalling S in (2.14), we define

$$\beta_1' := \min \{ S^2/(4d_1), \beta_1 \}.$$
 (3.1)

Fix any $\beta \in (0, \beta_1')$ and define

$$c_{\beta} := \inf_{\vec{u} \in \mathcal{K}_{\beta}} E_{\beta}(\vec{u}); \quad \mathcal{K}_{\beta} := \{\vec{u} : \vec{u} \text{ is a sign-changing solution of } (1.2)\}.$$

Then $K_{\beta} \neq \emptyset$ and $c_{\beta} < d_1$. Let $\vec{u}_n = (u_{n,1}, u_{n,2}) \in K_{\beta}$ be a minimizing sequence of c_{β} with $E_{\beta}(\vec{u}_n) < d_1$ for all $n \geq 1$. Then $\|u_{n,1}\|_{\lambda_1}^2 + \|u_{n,2}\|_{\lambda_2}^2 < 4d_1$. Up to a subsequence, we may assume that $\vec{u}_n \to \vec{u} = (u_1, u_2)$ weakly in H and strongly in $L^4(\Omega) \times L^4(\Omega)$. Since $E'_{\beta}(\vec{u}_n) = 0$, it is standard to prove that $\vec{u}_n \to \vec{u} = (u_1, u_2)$ strongly in H, $E'_{\beta}(\vec{u}) = 0$ and $E_{\beta}(\vec{u}) = c_{\beta}$. On the other hand, we deduce from $E'_{\beta}(\vec{u}_n)(u_{n,1}^{\pm}, 0) = 0$ and $E'_{\beta}(\vec{u}_n)(0, u_{n,2}^{\pm}) = 0$ that

$$S|u_{n,i}^{\pm}|_{4}^{2} \leq ||u_{n,i}^{\pm}||_{\lambda_{i}}^{2} = \mu_{i}|u_{n,i}^{\pm}|_{4}^{4} + \beta \int_{\Omega} |u_{n,i}^{\pm}|^{2}u_{n,j}^{2}dx \leq \mu_{i}|u_{n,i}^{\pm}|_{4}^{4} + \beta |u_{n,i}^{\pm}|_{4}^{2}|u_{n,j}|_{4}^{2}$$

$$\leq \mu_{i}|u_{n,i}^{\pm}|_{4}^{4} + \frac{\beta}{S}|u_{n,i}^{\pm}|_{4}^{2}||u_{n,j}||_{\lambda_{j}}^{2} < \mu_{i}|u_{n,i}^{\pm}|_{4}^{4} + \frac{4d_{1}\beta}{S}|u_{n,i}^{\pm}|_{4}^{2},$$

which implies that $|u_{n,i}^{\pm}|_4 \geq C > 0$ for all $n \geq 1$ and i = 1, 2, where C is a constant independent of n and i. Hence $|u_i^{\pm}|_4 \geq C$ and so \vec{u} is a least energy sign-changing solution of (1.2).

4 Proof of Theorems 1.3

The following arguments are similar to those in Section 2 with some modifications. Here, although some definitions are slight different from those in Section 2, we will use the same notations as in Section 2 for convenience. To obtain semi-nodal solutions (u_1, u_2) such that u_1 changes sign and u_2 is positive, we consider the following functional

$$\widetilde{E}_{\beta}(u_1, u_2) := \frac{1}{2} \left(\|u_1\|_{\lambda_1}^2 + \|u_2\|_{\lambda_2}^2 \right) - \frac{1}{4} \left(\mu_1 |u_1|_4^4 + \mu_2 |u_2^+|_4^4 \right) - \frac{\beta}{2} \int_{\Omega} u_1^2 u_2^2 \, dx,$$

and modify the definition of \widetilde{H} by $\widetilde{H} := \{(u_1, u_2) \in H : u_1 \neq 0, u_2^+ \neq 0\}$. Then by similar proofs as in Section 2, we have the following lemma.

Lemma 4.1. For any $\vec{u} = (u_1, u_2) \in \widetilde{H}$, if

$$\begin{cases}
\mu_{2}|u_{2}^{+}|_{4}^{4}||u_{1}||_{\lambda_{1}}^{2} - \beta||u_{2}||_{\lambda_{2}}^{2} \int_{\Omega} u_{1}^{2}u_{2}^{2} dx > 0, \\
\mu_{1}|u_{1}|_{4}^{4}||u_{2}||_{\lambda_{2}}^{2} - \beta||u_{1}||_{\lambda_{1}}^{2} \int_{\Omega} u_{1}^{2}u_{2}^{2} dx > 0,
\end{cases}$$
(4.1)

then system

$$\begin{cases} \|u_1\|_{\lambda_1}^2 = t_1 \mu_1 |u_1|_4^4 + t_2 \beta \int_{\Omega} u_1^2 u_2^2 dx \\ \|u_2\|_{\lambda_2}^2 = t_2 \mu_2 |u_2^+|_4^4 + t_1 \beta \int_{\Omega} u_1^2 u_2^2 dx \end{cases}$$
(4.2)

has a unique solution

$$\begin{cases}
t_{1}(\vec{u}) = \frac{\mu_{2}|u_{2}^{+}|_{4}^{4}|u_{1}|_{\lambda_{1}}^{2} - \beta|u_{2}|_{\lambda_{2}}^{2} \int_{\Omega} u_{1}^{2}u_{2}^{2} dx}{\mu_{1}\mu_{2}|u_{1}|_{4}^{4}|u_{2}^{+}|_{4}^{4} - \beta^{2}(\int_{\Omega} u_{1}^{2}u_{2}^{2} dx)^{2}} > 0 \\
t_{2}(\vec{u}) = \frac{\mu_{1}|u_{1}|_{4}^{4}|u_{2}||_{\lambda_{2}}^{2} - \beta|u_{1}||_{\lambda_{1}}^{2} \int_{\Omega} u_{1}^{2}u_{2}^{2} dx}{\mu_{1}\mu_{2}|u_{1}|_{4}^{4}|u_{2}^{+}|_{4}^{4} - \beta^{2}(\int_{\Omega} u_{1}^{2}u_{2}^{2})^{2} dx} > 0.
\end{cases} (4.3)$$

Moreover,

$$\sup_{t_1, t_2 \ge 0} \widetilde{E}_{\beta} \left(\sqrt{t_1} u_1, \sqrt{t_2} u_2 \right) = \widetilde{E}_{\beta} \left(\sqrt{t_1(\vec{u})} u_1, \sqrt{t_2(\vec{u})} u_2 \right)
= \frac{1}{4} \frac{\mu_2 |u_2^+|_4^4 ||u_1||_{\lambda_1}^4 - 2\beta ||u_1||_{\lambda_1}^2 ||u_2||_{\lambda_2}^2 \int_{\Omega} u_1^2 u_2^2 dx + \mu_1 |u_1|_4^4 ||u_2||_{\lambda_2}^4}{\mu_1 \mu_2 |u_1|_4^4 |u_2^+|_4^4 - \beta^2 (\int_{\Omega} u_1^2 u_2^2 dx)^2}$$
(4.4)

and $(t_1(\vec{u}), t_2(\vec{u}))$ is the unique maximum point of $\widetilde{E}_{\beta}(\sqrt{t_1}u_1, \sqrt{t_2}u_2)$.

Now we modify the definitions of \mathcal{M}^* , \mathcal{M}^*_{β} , \mathcal{M}^{**}_{β} , \mathcal{M} and \mathcal{M}_{β} by

$$\mathcal{M}^* := \left\{ \vec{u} \in H : 1/2 < |u_1|_4^4 < 2, \ 1/2 < |u_2^+|_4^4 < 2 \right\};$$

$$\mathcal{M}^*_{\beta} := \left\{ \vec{u} \in \mathcal{M}^* : \vec{u} \text{ satisfies (4.1)} \right\};$$

$$(4.5)$$

$$\mathcal{M}_{\beta}^{**} := \left\{ \vec{u} \in \mathcal{M}^{*} : \begin{array}{l} \mu_{2} \|u_{1}\|_{\lambda_{1}}^{2} - \beta \|u_{2}\|_{\lambda_{2}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx > 0 \\ \mu_{1} \|u_{2}\|_{\lambda_{2}}^{2} - \beta \|u_{1}\|_{\lambda_{1}}^{2} \int_{\Omega} u_{1}^{2} u_{2}^{2} dx > 0 \end{array} \right\};$$

$$\mathcal{M} := \left\{ \vec{u} \in H : |u_{1}|_{4} = 1, |u_{2}^{+}|_{4} = 1 \right\}, \quad \mathcal{M}_{\beta} := \mathcal{M} \cap \mathcal{M}_{\beta}^{*}, \tag{4.6}$$

and define a new functional $J_{\beta}: \mathcal{M}_{\beta}^{**} \to (0, +\infty)$ as in Section 2 by

$$J_{\beta}(\vec{u}) := \frac{1}{4} \frac{\mu_2 \|u_1\|_{\lambda_1}^4 - 2\beta \|u_1\|_{\lambda_1}^2 \|u_2\|_{\lambda_2}^2 \int_{\Omega} u_1^2 u_2^2 dx + \mu_1 \|u_2\|_{\lambda_2}^4}{\mu_1 \mu_2 - \beta^2 (\int_{\Omega} u_1^2 u_2^2 dx)^2}.$$

Then $J_{\beta} \in C^1(\mathcal{M}_{\beta}^{**}, (0, +\infty))$ and (2.8)-(2.9) hold for any $\vec{u} \in \mathcal{M}_{\beta}$ and $\varphi, \psi \in H_0^1(\Omega)$. Moreover, Lemma 4.1 yields

$$J_{\beta}(u_1, u_2) = \sup_{t_1, t_2 > 0} \widetilde{E}_{\beta} \left(\sqrt{t_1} u_1, \sqrt{t_2} u_2 \right), \quad \forall (u_1, u_2) \in \mathcal{M}_{\beta}.$$
 (4.7)

Under this new definitions (4.5)-(4.6), we define \mathcal{N}_b^* and \mathcal{N}_b as in (2.11)-(2.13). Since $|u_2|_4^2 \leq S^{-1} ||u_2||_{\lambda_2}^2 \leq b/S$ for all $\vec{u} \in \mathcal{N}_b^*$, by trivial modifications it is easy to check that Lemmas 2.2 and 2.3 also hold here. Moreover, we may assume that (2.16) also holds here for any $\beta \in (0, \beta_k)$.

Now we fix any $\beta \in (0, \beta_k)$. For any $\vec{u} = (u_1, u_2) \in \mathcal{N}_b^*$, let $\tilde{w}_i \in H_0^1(\Omega)$, i = 1, 2, be the unique solutions of the following linear problem

$$\begin{cases}
-\Delta \tilde{w}_1 + \lambda_1 \tilde{w}_1 - \beta t_2(\vec{u}) u_2^2 \tilde{w}_1 = \mu_1 t_1(\vec{u}) u_1^3, & \tilde{w}_1 \in H_0^1(\Omega), \\
-\Delta \tilde{w}_2 + \lambda_2 \tilde{w}_2 - \beta t_1(\vec{u}) u_1^2 \tilde{w}_2 = \mu_2 t_2(\vec{u}) (u_2^+)^3, & \tilde{w}_2 \in H_0^1(\Omega).
\end{cases}$$
(4.8)

As in Section 2, we define

$$w_i = \alpha_i \tilde{w}_i$$
, where $\alpha_1 = \frac{1}{\int_{\Omega} u_1^3 \tilde{w}_1 dx} > 0$, $\alpha_2 = \frac{1}{\int_{\Omega} (u_2^+)^3 \tilde{w}_2 dx} > 0$. (4.9)

Then (w_1, w_2) is the unique solution of the problem

$$\begin{cases}
-\Delta w_1 + \lambda_1 w_1 - \beta t_2(\vec{u}) u_2^2 w_1 = \alpha_1 \mu_1 t_1(\vec{u}) u_1^3, & w_1 \in H_0^1(\Omega), \\
-\Delta w_2 + \lambda_2 w_2 - \beta t_1(\vec{u}) u_1^2 w_2 = \alpha_2 \mu_2 t_2(\vec{u}) (u_2^+)^3, & w_2 \in H_0^1(\Omega), \\
\int_{\Omega} u_1^3 w_1 dx = 1, & \int_{\Omega} (u_2^+)^3 w_2 dx = 1.
\end{cases} (4.10)$$

As in Section 2, the operator $K = (K_1, K_2) : \mathcal{N}_b^* \to H$ is defined as $K(\vec{u}) := \vec{w} = (w_1, w_2)$, and similar arguments as Lemma 2.4 yield $K \in C^1(\mathcal{N}_b^*, H)$. Since $u_n \to u$ in $L^4(\Omega)$ implies $u_n^+ \to u^+$ in $L^4(\Omega)$, so Lemma 2.5 also holds for this new K defined here. Clearly

$$K(\sigma_1(\vec{u})) = \sigma_1(K(\vec{u})). \tag{4.11}$$

Remark that (4.11) only holds for σ_1 and in the sequel we only use σ_1 . Consider

$$\mathcal{F} = \{ A \subset \mathcal{M} : A \text{ is closed and } \sigma_1(\vec{u}) \in A \ \forall \ \vec{u} \in A \},$$

and, for each $A \in \mathcal{F}$ and $k_1 \geq 2$, the class of functions

$$F_{(k_1,1)}(A) = \{ f : A \to \mathbb{R}^{k_1-1} : f \text{ continuous and } f(\sigma_1(\vec{u})) = -f(\vec{u}) \}.$$

Definition 4.1. (Modified vector genus, slightly different from Definition 2.1) Let $A \in \mathcal{F}$ and take any $k_1 \in \mathbb{N}$ with $k_1 \geq 2$. We say that $\vec{\gamma}(A) \geq (k_1, 1)$ if for every $f \in F_{(k_1, 1)}(A)$ there exists $\vec{u} \in A$ such that $f(\vec{u}) = 0$. We denote

$$\Gamma^{(k_1,1)} := \{ A \in \mathcal{F} : \vec{\gamma}(A) \ge (k_1,1) \}.$$

Lemma 4.2. (see [10, Lemma 4.2]) With the previous notations, the following properties hold.

- (i) Take $A := A_1 \times A_2 \subset \mathcal{M}$ and let $\eta : S^{k_1-1} \to A_1$ be a homeomorphism such that $\eta(-x) = -\eta(x)$ for every $x \in S^{k_1-1}$. Then $A \in \Gamma^{(k_1,1)}$.
- (ii) We have $\overline{\eta(A)} \in \Gamma^{(k_1,1)}$ whenever $A \in \Gamma^{(k_1,1)}$ and a continuous map $\eta : A \to \mathcal{M}$ is such that $\eta \circ \sigma_1 = \sigma_1 \circ \eta$.

Now we modify the definitions of \mathcal{P} and $\operatorname{dist}_4(\vec{u},\mathcal{P})$ in (2.23)-(2.24) by

$$\mathcal{P} := \mathcal{P}_1 \cup -\mathcal{P}_1, \quad \text{dist}_4(\vec{u}, \mathcal{P}) := \min \left\{ \text{dist}_4(u_1, \mathcal{P}_1), \, \text{dist}_4(u_1, -\mathcal{P}_1) \right\}.$$
 (4.12)

Under this new definition, u_1 changes sign if $\operatorname{dist}_4(\vec{u}, \mathcal{P}) > 0$.

Lemma 4.3. (see [10, Lemma 4.3]) Let $k_1 \geq 2$. Then for any $\delta < 2^{-1/4}$ and any $A \in \Gamma^{(k_1,1)}$ there holds $A \setminus \mathcal{P}_{\delta} \neq \emptyset$.

Lemma 4.4. There exists $A \in \Gamma^{(k+1,1)}$ such that $A \subset \mathcal{N}_b$ and $\sup_A J_{\beta} < d_k$.

Proof. Recalling $\varphi_0 \in W_{k+1}$ is positive, we define

$$A_1 := \{ u \in W_{k+1} : |u|_4 = 1 \}, \quad A_2 := \{ C\varphi_0 : C = 1/|\varphi_0|_4 \}.$$

Then by Lemma 4.2-(i) one has $A := A_1 \times A_2 \in \Gamma^{(k+1,1)}$. The rest of the proof is the same as Lemma 2.8.

For every $k_1 \in [2, k+1]$ and $0 < \delta < 2^{-1/4}$, we define

$$c_{\beta,\delta}^{k_1,1} := \inf_{A \in \Gamma_\beta^{(k_1,1)}} \sup_{\vec{u} \in A \backslash \mathcal{P}_\delta} J_\beta(\vec{u}),$$

where the definition of $\Gamma_{\beta}^{(k_1,1)}$ is the same as (2.26). Then Lemma 4.4 yields $\Gamma_{\beta}^{(k_1,1)} \neq \emptyset$ and so $c_{\beta,\delta}^{k_1,1}$ is well defined for each $k_1 \in [2,k+1]$. Moreover, $c_{\beta,\delta}^{k_1,1} < d_k$ for any $\delta \in (0,2^{-1/4})$ and $k_1 \in [2,k+1]$. Define $\mathcal{N}_{b,\beta} := \{\vec{u} \in \mathcal{N}_b : J_{\beta}(\vec{u}) < d_k\}$ as in Section 2. Under the new definition (4.12), it is easy to see that Lemma 2.9 also holds here. Now as in Section 2, we define a map $V : \mathcal{N}_b^* \to H$ by $V(\vec{u}) := \vec{u} - K(\vec{u})$. Then Lemma 2.10 also holds here. Recall from (4.6) and (4.10) that $\int_{\Omega} (u_2^+)^3 (u_2 - w_2) dx = 1 - 1 = 0$ for any $\vec{u} = (u_1, u_2) \in \mathcal{N}_b$. Then by similar arguments, we see that Lemma 2.11 also holds here.

Lemma 4.5. There exists a unique global solution $\eta = (\eta_1, \eta_2) : [0, \infty) \times \mathcal{N}_{b,\beta} \to H$ for the initial value problem

$$\frac{d}{dt}\eta(t,\vec{u}) = -V(\eta(t,\vec{u})), \quad \eta(0,\vec{u}) = \vec{u} \in \mathcal{N}_{b,\beta}. \tag{4.13}$$

Moreover, conclusions (i), (iii) and (iv) of Lemma 2.12 also hold here, and $\eta(t, \sigma_1(\vec{u})) = \sigma_1(\eta(t, \vec{u}))$ for any t > 0 and $u \in \mathcal{N}_{b,\beta}$.

Proof. Recalling $V(\vec{u}) \in C^1(\mathcal{N}_b^*, H)$, we see that (4.13) has a unique solution $\eta: [0, T_{\max}) \times \mathcal{N}_{b,\beta} \to H$, where $T_{\max} > 0$ is the maximal time such that $\eta(t, \vec{u}) \in \mathcal{N}_b^*$ for all $t \in [0, T_{\max})$. Fix any $\vec{u} = (u_1, u_2) \in \mathcal{N}_{b,\beta}$, we deduce from (4.13) that $\frac{d}{dt} \int_{\Omega} (\eta_2(t, \vec{u})^+)^4 dx = 4 - 4 \int_{\Omega} (\eta_2(t, \vec{u})^+)^4 dx$, $\forall 0 < t < T_{\max}$. Since $\int_{\Omega} (\eta_2(0, \vec{u})^+)^4 dx = \int_{\Omega} (u_2^+)^4 dx = 1$, so $\int_{\Omega} (\eta_2(t, \vec{u})^+)^4 dx \equiv 1$ for all $0 \le t < T_{\max}$. Recalling (4.11), we see that the rest of the proof is similar to Lemma 2.12.

Proof of Theorem 1.3. First we fix any $k_1 \in [2, k+1]$. Then by similar arguments as Step 1 in the proof of Theorem 1.1, for small $\delta > 0$, there exists $\vec{u} = (u_1, u_2) \in \mathcal{N}_b$ such that

$$J_{\beta}(\vec{u}) = c_{\beta,\delta}^{k_1,1}, \quad V(\vec{u}) = 0 \quad \text{and } \operatorname{dist}_4(\vec{u}, \mathcal{P}) \ge \delta.$$

So u_1 changes sign. Since $V(\vec{u}) = 0$, so $\vec{u} = K(\vec{u})$. Combining this with (4.10), we see that \vec{u} satisfies

$$\begin{cases}
-\Delta u_1 + \lambda_1 u_1 = \alpha_1 \mu_1 t_1(\vec{u}) u_1^3 + \beta t_2(\vec{u}) u_2^2 u_1, \\
-\Delta u_2 + \lambda_2 u_2 = \alpha_2 \mu_2 t_2(\vec{u}) (u_2^+)^3 + \beta t_1(\vec{u}) u_1^2 u_2.
\end{cases}$$
(4.14)

Since $|u_1|_4 = 1$, $|u_2^+|_4 = 1$ and $t_i(\vec{u})$ satisfies (4.2), so $\alpha_1 = \alpha_2 = 1$. Multiplying the second equation of (4.14) by u_2^- and integrating over Ω , we see from (2.16) that $||u_2^-||^2_{\lambda_2} = 0$, so $u_2 \geq 0$. By the strong maximum principle, $u_2 > 0$ in Ω . Hence $(\tilde{u}_1, \tilde{u}_2) := (\sqrt{t_1(\vec{u})}u_1, \sqrt{t_2(\vec{u})}u_2)$ is a semi-nodal solution of the original problem (1.2) with \tilde{u}_1 sign-changing and \tilde{u}_2 positive. Moreover, (4.4) and (4.7) yield $E_{\beta}(\tilde{u}_1, \tilde{u}_2) = \tilde{E}_{\beta}(\tilde{u}_1, \tilde{u}_2) = J_{\beta}(u_1, u_2) = c_{\beta, \delta}^{k_1, 1} < d_k$. Finally, since $k_1 \in [2, k+1]$, by similar arguments as Step 2 of proving Theorem 1.1 with trivial modifications, we can prove that (1.2) has at least k semi-nodal solutions. This completes the proof.

Remark 4.1. By a similar argument as in Section 3, we can prove that there exists $\beta_1'' > 0$ such that for any $\beta \in (0, \beta_1'')$, (1.2) has a semi-nodal solution which has the least energy among all semi-nodal solutions.

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